

# FIXED PARAMETER ALGORITHMS FOR COMPLETION PROBLEMS ON PLANE GRAPHS

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in collaboration with

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# THE SUBGRAPH & MINOR ISOMORPHISM PROBLEMS

The **SUBGRAPH ISOMORPHISM PROBLEM (S.I.)** and the **MINOR ISOMORPHISM PROBLEM (M.I.)** (also known as **MINOR CONTAINMENT**) are two well-known **NP-complete** problems that accept as input two graphs  $G$  and  $H$  and check whether  $G$  has any subgraph or minor isomorphic to  $H$ .

	General	Planar
S.I.	?	$2^{O(k)} \cdot n$ (Eppstein 1999)
M.I.	$g(k) \cdot n^3$ (Robertson & Seymour 1995)	$O(2^{O(k)} \cdot n + n^2 \cdot \log n)$ (Adler et al. 2010)

where  $n = |V(G)|$  and  $k = |V(H)|$ .

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- ★ A *planar* graph is a graph that **can be** embedded on the plane such that no two of its edges intersect, apart from any common endpoints.
- ★ A *plane* graph is a graph **embedded** on the plane, so that its vertices are points and its edges are arcs. Each plane graph can be naturally associated to a planar graph through isomorphism.
- ★ The plane graphs can be regarded as “drawings” or embeddings of the planar graphs on the plane.
- ★ A planar graph can have infinitely many embeddings but only finite (at most factorial) different up to topological isomorphism.

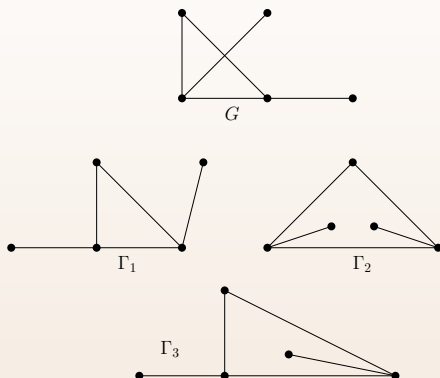
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# PLANAR AND PLANE GRAPHS CONT'D

For example:



Here,  $G$  is a planar graph and  $\Gamma_1$ ,  $\Gamma_2$ , and  $\Gamma_3$  are planar embeddings of  $G$ . In fact,  $\Gamma_1$  and  $\Gamma_2$  are equivalent (topologically isomorphic) to each other but not to  $\Gamma_3$ .



# COMPLETION PROBLEMS

Problem:  $\Pi$

Input: Graphs  $G_1, \dots, G_l$

Question: Do the graphs have a specified property  $P$ ?

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Many interesting problems, naturally parameterized by the number of new edges ( $k$ ), arose with the introduction of the completion operation, which have been studied a lot lately.

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# THE PLANE SUBGRAPH COMPLETION PROBLEM

## PLANE SUBGRAPH COMPLETION (PSC)

Input: A “host” plane graph  $\Gamma$  and a “pattern” **connected** plane graph  $\Delta$ .

Parameter:  $k = |V(\Delta)|$

Question: Can we add edges to  $\Gamma$  so that it contains a subgraph topologically isomorphic to  $\Delta$  **while remaining planar**?



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$\Delta$

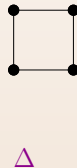
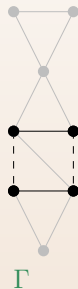
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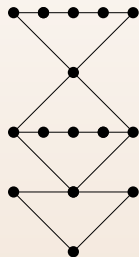
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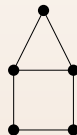
Input: A “host” plane graph  $\Gamma$  and a “pattern” **connected** plane graph  $\Delta$ .

Parameter:  $k = |V(\Delta)|$

Question: Can we add edges to  $\Gamma$  so that it contains a topological minor topologically isomorphic to  $\Delta$  **while remaining planar**?



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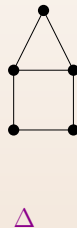
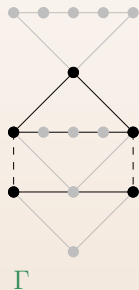
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If  $k := |V(\Delta)|$  and  $n := |V(\Gamma)|$ , we give:

- an FPT algorithm for **PSC** that runs in time  $2^{O(k \log k)} \cdot n^2$  and
- an FPT algorithm for **PTMC** that runs in time  $g(k) \cdot n^2$ .

*Remark.* In fact we can even solve more general problems: we can ask that the pattern graph  $\Delta$  be given as a **planar** graph and check whether **any** of its embeddings can be found in the host.



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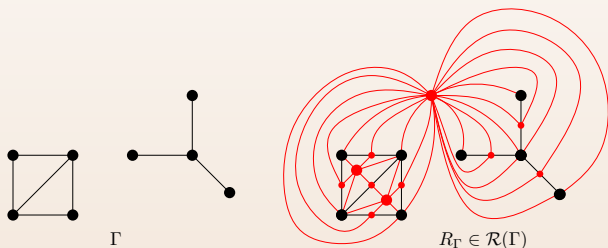


First, let's see the tools we need for the **PSC**-algorithm...

# SUBDIVIDED RADIAL ENHANCEMENT

A *subdivided radial enhancement* of a plane graph  $\Gamma$  is a **plane multigraph**  $R_\Gamma$ , that can be constructed from  $\Gamma$  by subdividing each edge of the graph once and then adding a vertex inside each face and connecting it with all the vertices of the face, so that in the resulting graph embedding each face with at least one original edge is a triangle.

Example:



From now on we will call this construction just *enhancement*.

# SOME OBSERVATIONS

Let's consider some facts about this construction.

- If  $\Gamma$  is **disconnected**, then the **enhancement** is connected but it can be done in (exponentially) many ways.
- If  $\Gamma$  is **connected**, then the **enhancement** is uniquely defined (and in fact 2-connected).
- If  $\Gamma$  is **2-connected**, then the **enhancement** is 3-connected.

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# THE PSC-ALGORITHM

Input:



$\Gamma$



$\Delta$

# THE PSC-ALGORITHM

Step 1: Guess which edges of  $\Delta$  (red) are missing from  $\Gamma$ . This is much easier than guessing which edges should be added to  $\Gamma$ .

$O(2^k)$  time



$\Gamma$

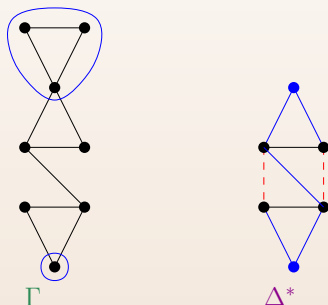


$\Delta$

# THE PSC-ALGORITHM

Step 2: Guess a supergraph  $\Delta^*$  of  $\Delta$  with extra (blue) vertices and edges in some faces that represent vertices and edges of  $\Gamma$  inside the corresponding faces. Then remove the red edges.

$O(2^{k \log k})$  time

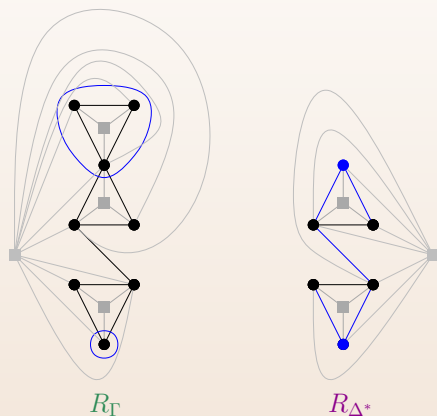




# THE PSC-ALGORITHM

Step 3: Enhance  $\Gamma$  arbitrarily and “guess” an enhancement of  $\Delta^*$ , resulting in  $R_\Gamma$  and  $R_{\Delta^*}$  respectively.

$O(n + 2^k)$  time



Step 4: Enhance twice more both of the graphs. This is to ensure that both of the resulting graphs  $Q(\Gamma)$  and  $Q(\Delta)$  are 3-connected and therefore, due to *Whitney's* theorem, uniquely embeddable.

$O(n + k)$  time

Step 5: Pick a vertex  $u$  of  $\Gamma$  and contract everything in  $Q(\Gamma)$  that is at a distance greater than  $\text{diam}(Q(\Delta)) = O(k)$  from  $u$ . It is easy to prove that the resulting graph  $Q_u(\Gamma)$  has treewidth  $\leq 3 \cdot \text{diam}(Q(\Delta)) = O(k)$ .

$O(n)$  time

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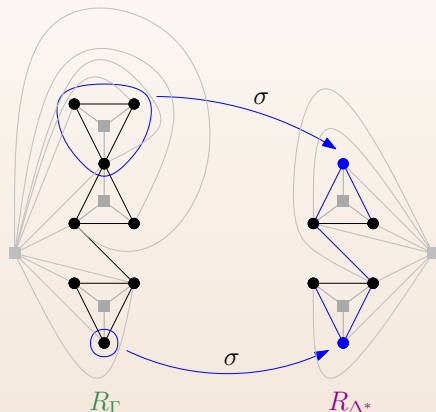
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# THE PSC-ALGORITHM

Step 6: Use a modified algorithm by Adler et al. (2011) to check whether **the planar graph**  $Q_u(\Gamma)$  contains **the planar graph**  $Q(\Delta)$  as a minor. This is easy since both of the graphs have now size  $O(k)$ . If the algorithm answered “NO”, go back to step 5 and pick a different vertex.

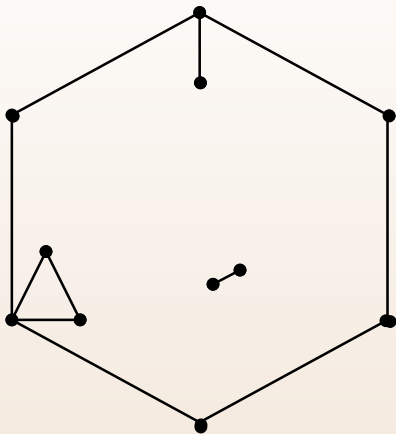
$\leq n$  steps



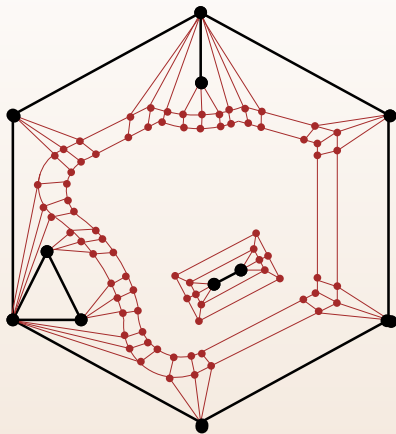


More tools are needed for the **PTMC**-algorithm...

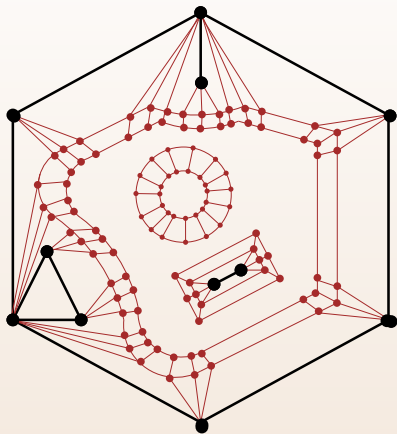
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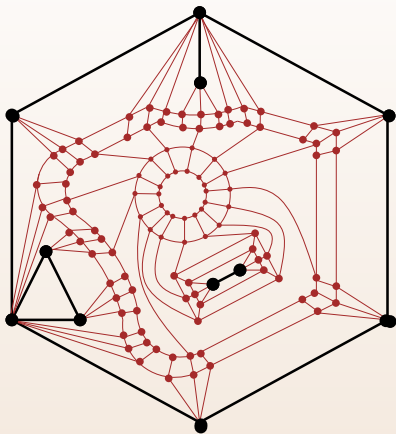


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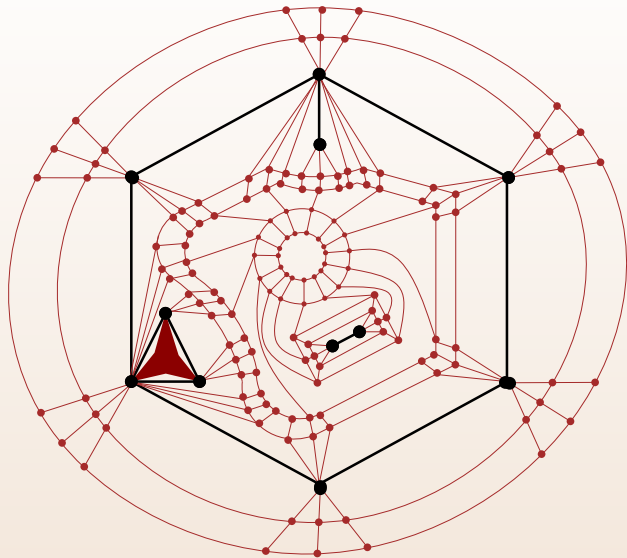




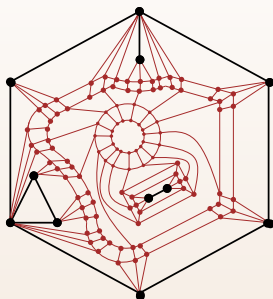
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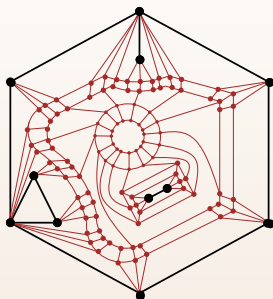


The resulting graph  $\Gamma^c$  has  $O(n)$  vertices.



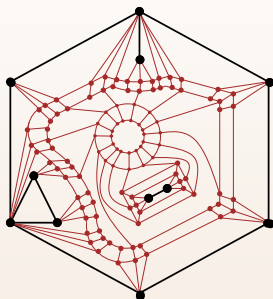
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- This special relation ( $\leq^*$ ) can be expressed in MSOL to find a top. minor that is **isomorphic** (not topologically isomorphic) to  $\Delta$ .

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# ROOTED DISJOINT PATHS

- To prove the previous claim, we use a result by Adler et al. (2011) which states that the number of edges that need to be added in each face in order to find  $k$  disjoint paths is bounded by  $f(k)$ .
- Using this result, we can solve the PLANAR ROOTED TOPOLOGICAL MINOR COMPLETION PROBLEM even for disconnected patterns and therefore the PLANAR DISJOINT PATHS COMPLETION PROBLEM.

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# THE IRRELEVANT-EDGE ALGORITHM

We combine two known algorithms in order to find an irrelevant edge in the graph (i.e., an edge whose removal results in an equivalent instance) in time  $g(k) \cdot n$ :

- by [Golovach, Kamiński, Maniatis, Thilikos \(2015\)](#), we find a large wall with some special properties in the graph and
- by [Kaminski, Thilikos \(2012\)](#), we find an irrelevant edge in the wall.



# THE PSC-ALGORITHM

Step 1: Cylindrically enhance  $\Gamma$  into  $\Gamma^c$ .

$O(n)$  time

Step 2: If  $\text{tw}(\Gamma^c) \leq f(k)$ , proceed to step 3. Otherwise, find an irrelevant edge in  $\Gamma^c$  and remove it. Repeat this step until the treewidth of the resulting graph  $\Gamma^{c-}$  is  $\leq f(k)$ .

$\leq g(k) \cdot n^2$  time

Step 3: Enhance twice  $\Gamma^{c-}$  and  $\Delta$ , resulting in  $\tilde{\Gamma}$  and  $\tilde{\Delta}$ .

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Step 4: Use Courcelle's algorithm to check whether  $\tilde{\Delta} \leq^* \tilde{\Gamma}$ .

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$\leq h(k) \cdot n$  time

- We can modify the **PSC**-algorithm to check if the pattern graph appears as **induced subgraph** in the host.
- Although the **PTMC**-algorithm works for **minors** as is, we can modify it slightly to obtain a linear algorithm (w.r.t.  $n$ ).
- Try to drop the super-exponential factor  $2^{O(k \log k)}$  of **PSC** to just exponential. A better way to “guess” the **blue** parts in the pattern will be needed.

# Thank you!

